

IN THE CLAIMS:

1. (Currently Amended) A method of detecting speech in an incoming signal comprising the steps of:

receiving said incoming signal, extracting an estimate of the noise background of the incoming signal and suppressing the noise background of the incoming signal to provide a noise suppressed signal in which the estimated background noise has been removed, filtering the noise suppressed signal in which the background noise has been removed with a spectral inverse filter, said spectral inverse filter is determined by spectrum maxima and the inverse filtering operation comprising the steps of:

in the logarithmic (dB) domain, removing the mean spectral magnitude from the original speech spectrum,

in the mean removed short term frequency spectrum $S(i)$, ($i=1 \dots 128$), determining all the frequency position (P_j), whose magnitudes are maxima over a window centered around P_j and stretching N positions to the left and right of P_j ,

in the list of peaks, adding the first ($i=1$) and last ($i=128$) frequency positions, their associated magnitudes set equal to the mean of the first and last $M \times N$ magnitudes, respectively, wherein said M and N are preset constants,

removing the mean of the peak magnitudes from each peak magnitude,

if the largest resulting peak magnitude exceeds a predetermined maximum peak value MAX_dB_DN , normalizing all peaks so that the largest peaks magnitude becomes MAX_Db_DN , and

the resulting inverse filtering $H(i)$, ($i=1 \dots 128$) is defined as the maximum of the normalized

peaks and 0 dB, and

removing the inverse filter from the original spectrum in the logarithmic domain $U(i) = S(i) - H(i)$ and measuring the periodicity of the signal from the inverse filter using an autocorrelation function to determine whether a signal frame corresponds ~~correspond~~ to a speech frame or not.

2. (Original) The method of claim 1 wherein said periodicity measurement is defined as:

$$\rho = \max_{T_l}^{T_h} R_x(\tau)$$

where T_l and T_h are pre-specified so that the period will range in the range of speech and the signal is speech if ρ is above a given threshold.

3. (Original) The method of Claim 2 wherein said period is between about 75 Hz and 400 Hz.

4. (Previously Presented) The method of claim 2 where said threshold value is set to maximize speech detection accuracy.

5. (Original) The method of claim 1 wherein said extracting step includes the steps of:
converting the spectrum of the incoming signal into logarithmic domain,
removing high frequency components in logarithmic domain by recurrent filtering along the time axis,

establishing an estimate of noise background, converting the estimate into linear domain, and
suppressing the noise background from the signal, in linear domain.

Claims 6-7 (Canceled)

8. (Currently Amended) The method of claim 10 ~~[[7]]~~ wherein said inverse filtering is performed in a log frequency domain and is implemented by subtracting from the original spectrum the estimated inverse filtering spectrum.

9. (Canceled)

10. (Currently Amended) A noise-resistant utterance detector comprising the steps of:
accepting a speech utterance input signal,
removing background noise from the utterance signal according to a spectral subtraction method to get a noise subtracted signal,

inverse filtering the noise subtracted signal with a spectral inverse filter to get an inverse filtered signal, wherein said spectral inverse filter is based on a normalized approximation of an envelope of a short term speech spectrum derived from a local maxima of said short term speech spectrum.

locating close low-frequency formants in the noise subtracted signal if they exist and inserting spectral valleys between said formants before said inverse filtering,

calculating the autocorrelation from the inverse filtered signal to get an autocorrelation result,
and

detecting that a frame of the signal being processed is or is not speech based on a threshold applied to the autocorrelation result.

11. (Currently Amended) The method of claim 10 wherein said spectral inverse filter is determined by ~~spectrum maxima and the inverse filtering operation~~ by the steps of:

in the logarithmic (dB) domain, removing the mean spectral magnitude from the original speech spectrum,

in the mean removed short term frequency spectrum $S(i)$, ($i=1...128$), determining all the frequency position (P_j), whose magnitudes are maxima over a window centered around P_j and stretching N positions to the left and right of P_j ,

in the list of peaks, adding the first ($i=1$) and last ($i=128$) frequency positions, their associated magnitudes set equal to the mean of the first and last M x N magnitudes, respectively, wherein said M and N are preset constants,

removing the mean of the peak magnitudes from each peak magnitude, and

if the largest resulting peak magnitude exceeds a predetermined maximum peak value MAX_dB_DN, normalizing all peaks so that the largest peaks magnitude becomes MAX_dB_DN,

wherein the resulting inverse ~~filter~~ ~~filtering~~ $H(i)$, ($i=1... 128$) is defined as the maximum of the normalized peaks and 0 dB, ~~and~~

~~removing the inverse filter from the original spectrum in the logarithmic domain $U(i) = S(i) - H(i)$.~~

12. (New) The method of claim 11 wherein said M, N and MAX_dB_DN are pre-selected to have the following values: M=5, N=3 and MAX_dB_DN=3.5 dB.

13. (New) The method of claim 1 wherein said M, N and MAX_dB_DN are pre-selected to have the following values: M=5, N=3 and MAX_dB_DN=3.5 dB.

14. (New) The method of claim 11 further comprising removing said inverse filter from the original spectrum in the logarithmic domain $U(i) = S(i) - H(i)$.

15. (New) A method of determining if a signal includes speech, comprising:

accepting an input signal;

removing background noise from said input signal according to a spectral subtraction method

to obtain a noise subtracted signal;

inverse filtering said noise subtracted signal with a spectral inverse filter to obtain an inverse filtered signal, wherein said inverse filtering is performed in a log frequency domain and is implemented by subtracting an estimated inverse filtering spectrum from an original spectrum of said input signal;

calculating the autocorrelation from said inverse filtered signal to get an autocorrelation result; and

detecting that a frame of said input signal is or is not speech based on a threshold applied to said autocorrelation result.